



日本航海学会
第131回講演会

Research on energy-saving performance analysis
for cargo handling operation of Hybrid Straddle Carrier

ハイブリット型ストラドルキャリアのコンテナ荷役時の
省エネ性能分析法に関する研究

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Background

- ✓ Kyoto Protocol 2005 – Reduce GHG Emission – Eco-Terminal – Pressure to container terminals to improve its facility for energy-saving
- ✓ Hybrid handling machineries is one of innovation expected to tackle the issue of reducing dependency to fossil fuel (In this case: Hybrid Straddle Carrier)

Problem Faced

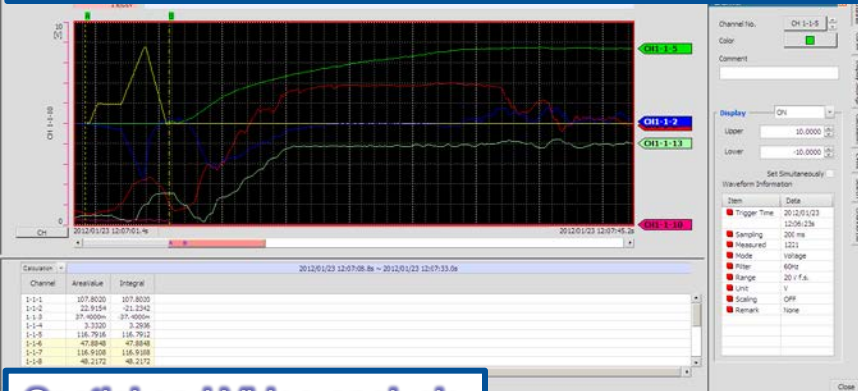
- ✓ Implication of the effort by container terminals is hardly to seen
- ✓ Operational performance of hybrid container handling machineries need to be improved considering high investment cost
- ✓ Energy analysis is normally performed from the aggregate data for whole facility or region
- ✓ Lack of detail analysis to provide better input to Container Terminals
- ✓ Necessity to extract more useful information from operational data

Objective

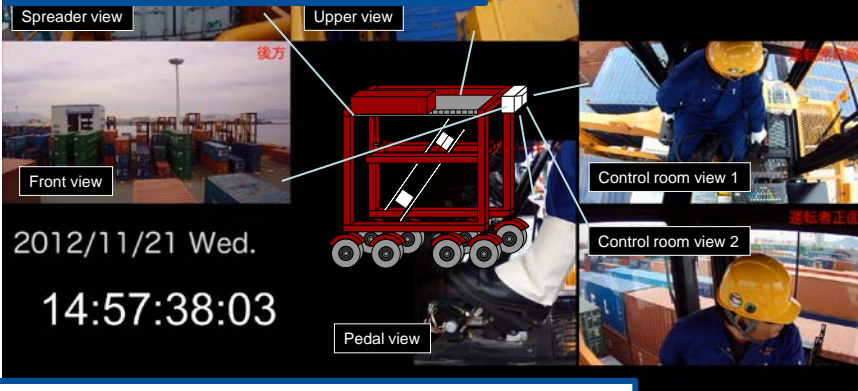
- ✓ Create visual energy analysis from operational database and model the operation of HSC to shows energy-saving impact of each kind of its operation.
- ✓ Improve the environmental footprint of Hybrid Straddle Carrier by efficient operation

What have we done previously

Performance measurement by data logging system



Spatial and Video analysis

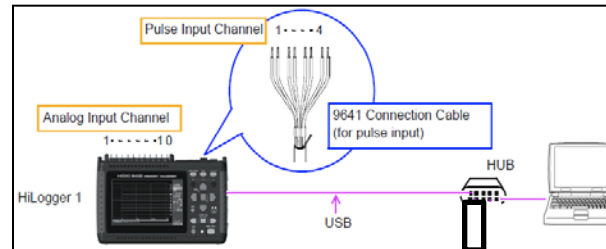


Analytical Model for Energy analysis

- Motion analysis
- Operation work code

		ACV (Converted)			
Speed (m/s)	battery (A)	fuel cons (L/h)	Weight (Ton)		
8	-15.740	4.17	0		
7	-11.737	3.28	27		
6	-6.964	1.70	0		
8	-8.387	5.19	24		
8	-4.777	1.73	0		
1452:40.0	1452:46	00:06.4	32	23.35	-9.79 12.92 17
7	14:54:07.6	14:54:14	00:06.4	32	32.93 -8.60 14.59
8	14:55:25.8	14:55:41	00:15.0	75	89.2^ 10.00 10.01
9	14:56:28.6	14:56:35	00:06.8	34	41.2 Measurement by Logger
10	14:57:21.6	14:57:44	00:22.2	111	146. Conversion by ACV
11	14:59:01.0	14:59:07	00:06.4	32	30.40 -0.00 14.00
12	15:00:01.2	15:00:07	00:05.8	29	16.91 -7.45 11.61 10
13	15:00:21.0	15:00:26	00:05.0	25	25.60 -5.18 7.77
14	15:00:42.0	15:00:50	00:07.6	38	30.35 -12.91 16.93 24
15	15:01:56.8	15:02:03	00:06.6	33	36.39 -8.51 15.71

No.	Measurement item	Measuring Range	Output Voltage
1	Output current of battery	±500 A	±10 V
2	Output current of converter	±500 A	±10 V
3	Lifting motor speed	±2000 RPM	±10 V
4	Lifting motor torque	±200 %	±10 V
5	Traveling motor speed (L/R)	±4000 RPM	±10 V
6	Traveling motor torque L/R)	±300 %	±10 V
7	Throttle opening angle	0 - 100 %	0 - 10 V
8	Brake pedal angle	0 - 100 %	0 - 10 V
9	Hoist operating lever angle	0 - 100 %	0 - 10 V
10	Steering reverser direction	forward/reverse/neutral	10V/0V/5V
11	Engine speed	0 - 2000 RPM	0 - 10 V
12	Bus voltage (DC)	0 - 2000 V	0 - 10 V
13	State of Charge	0 - 100 %	0 - 10 V
14	Twist lock	lock/unlock/neutral	10V/0V/5V
15	Weight	0 - 40 Ton	0 - 10 V
16	Fuel Consumption	0 - 70 L/h	0 - 10 V

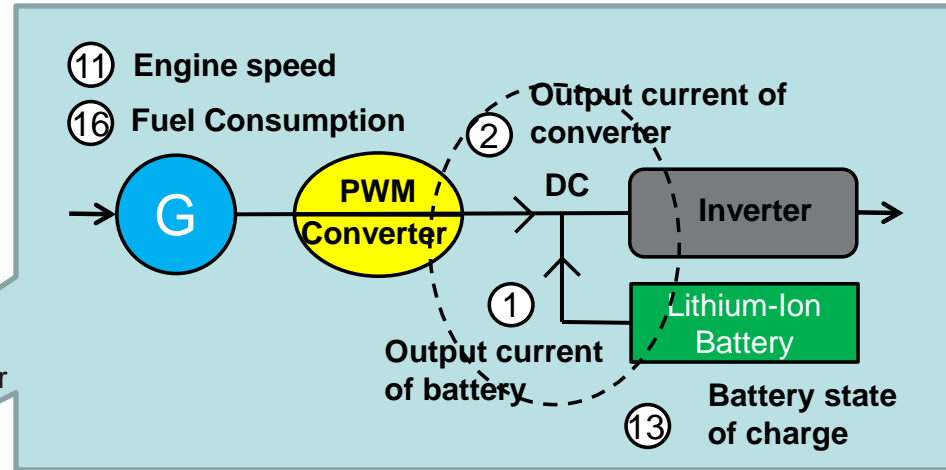
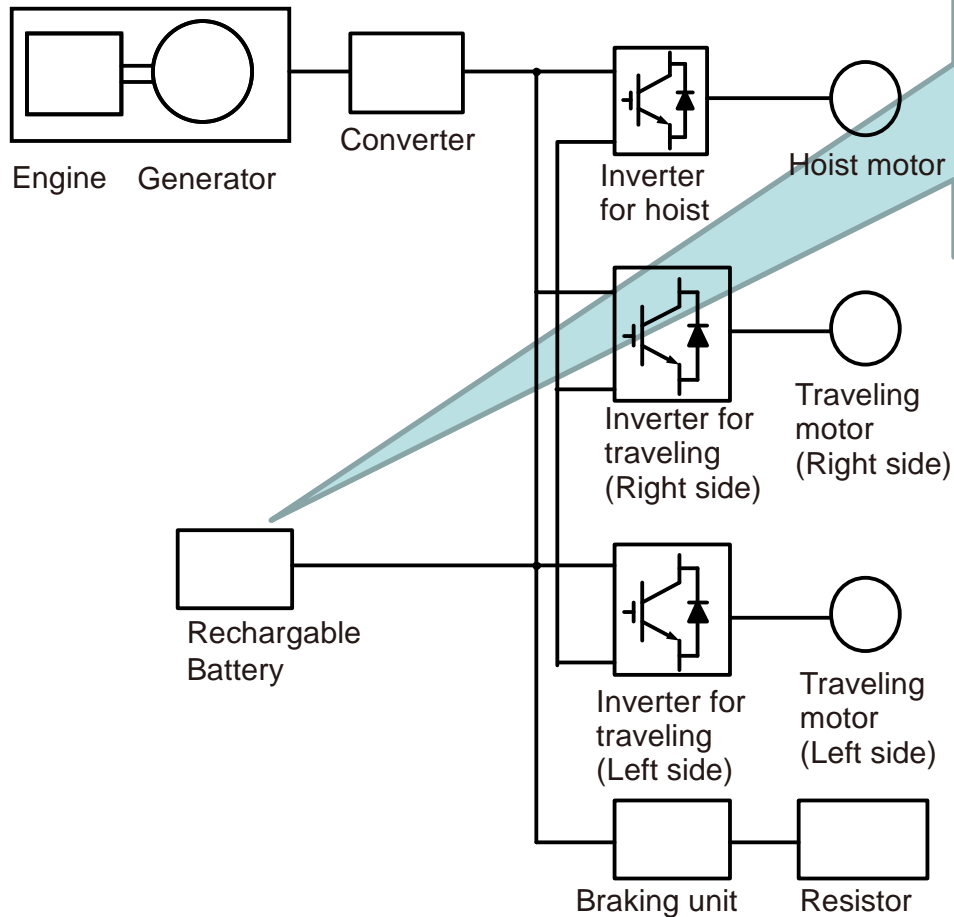


$$ACV = \left(\left(\sum_{i=1}^n di \times \Delta t \right) \div n \right) \times \left(\frac{M}{\theta} \right)$$

Integrating value
Averaging value
Converting value

Benefit of Regenerative Energy Stored in HSC's LITHIUM-ION Battery

Diesel-electric S/C system diagram

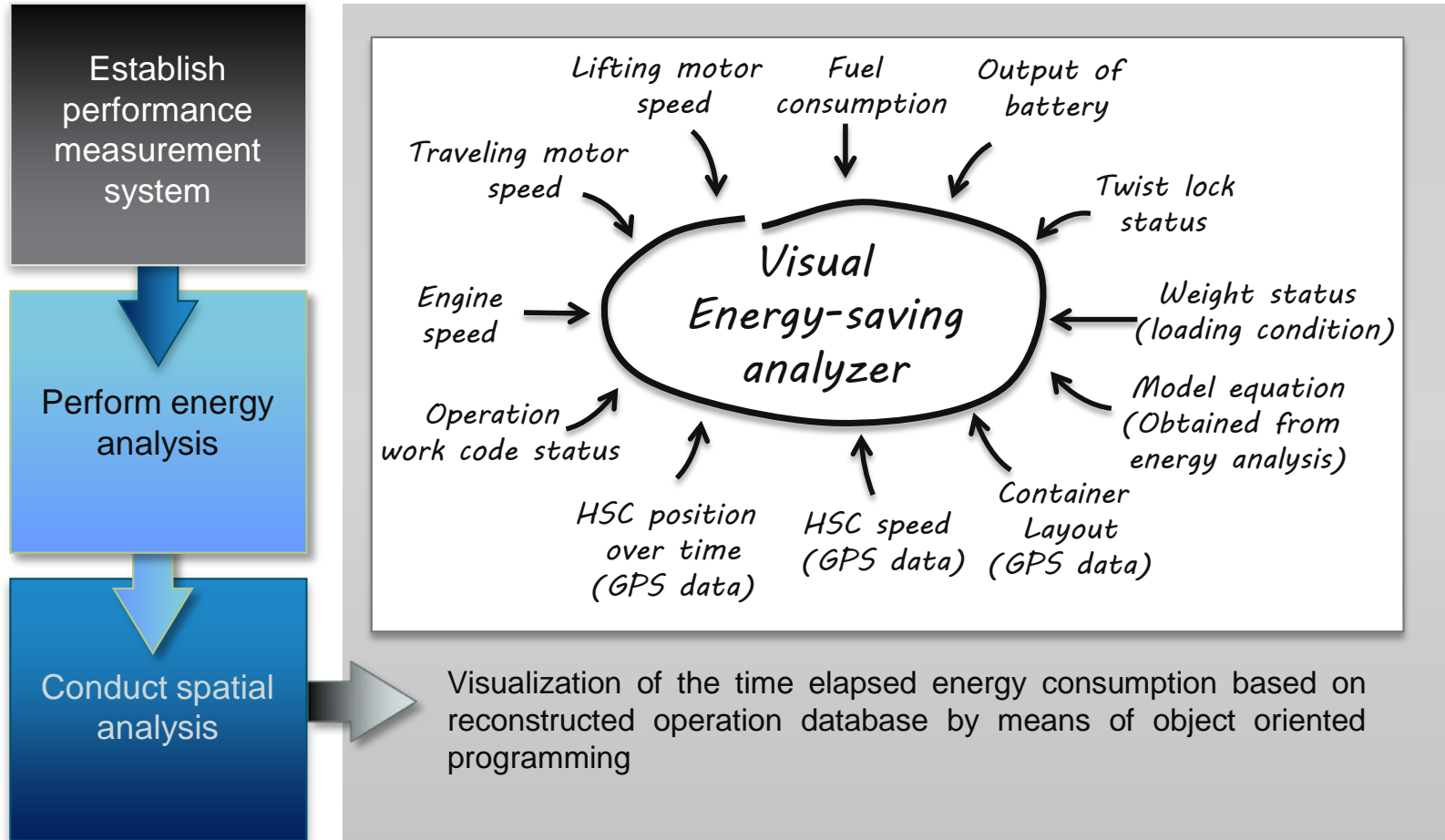


Hypotheses:

1. Output from Lithium Ion Battery which contain stored regenerative energy can be used to support load of generator
2. The effect is reduced fuel consumption when battery energy is discharged

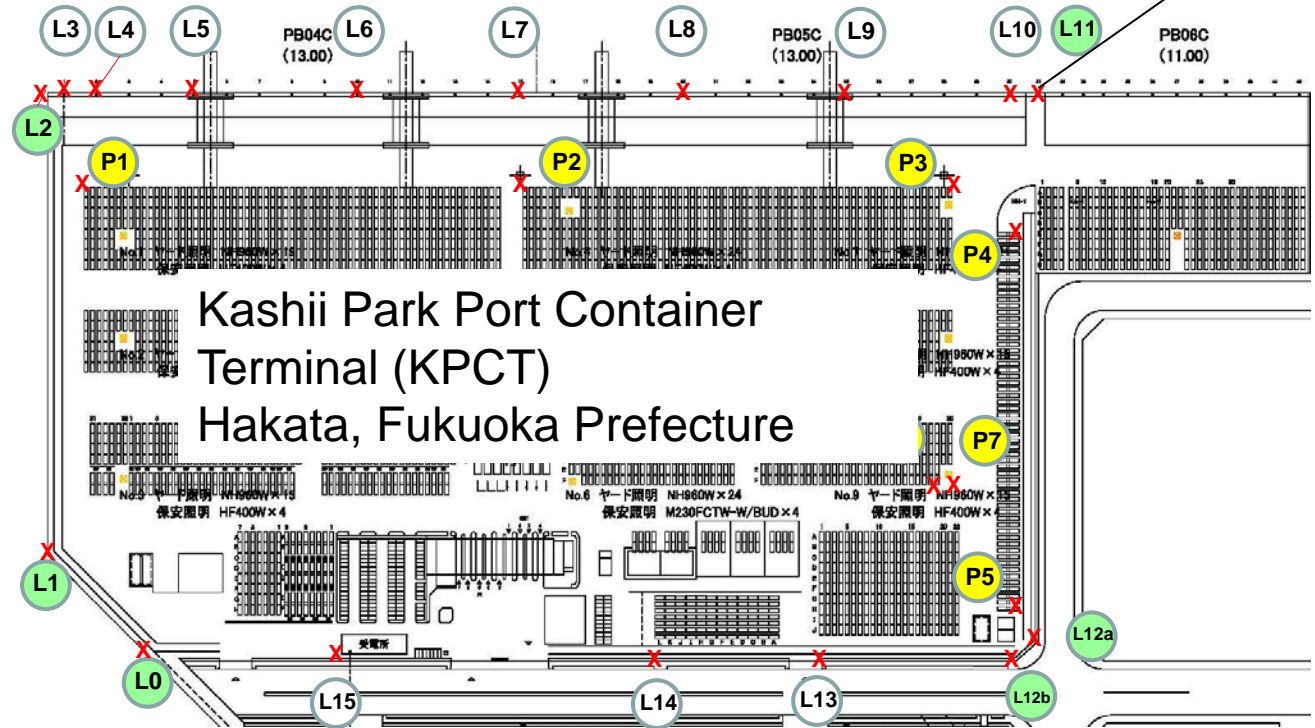
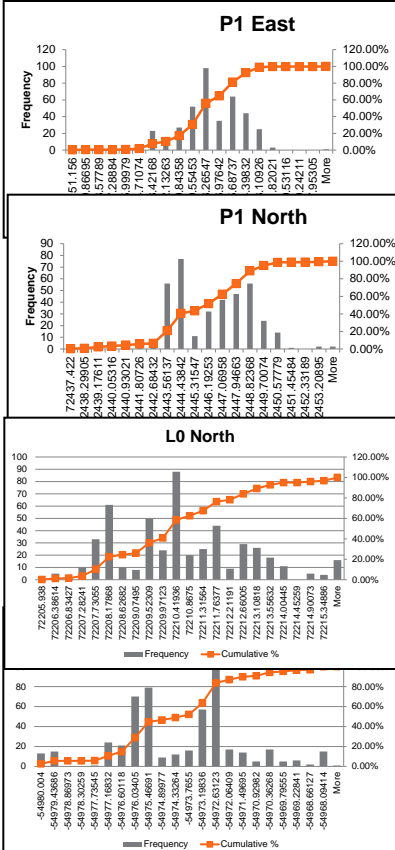
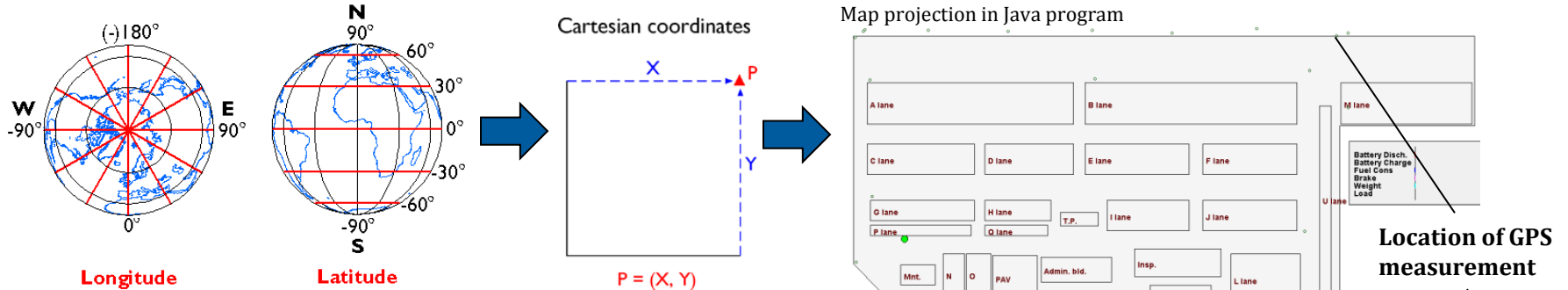
Visualizing energy analysis

Visualization of energy analysis able to extract various information from operation which were not able to be shown by previous method



Visualizing Container Layout in Plain Coordinate

Map projection : Transform geographic coordinate of container terminal to plane cartesian coordinate system (use of JGD 2000 Japan Zone 2 (Fukuoka))



Visualizing HSC movement in Plain Coordinate

Database Reconstruction

HSC movement measurement by GPS } Input for java program
 Data logger output }

1 Operation Work Code

Code	Denomination	Type of Operation
1	Delivery	Deliver container from CY to Outside Chassis (OC)
2	Receipt	Receive container from Outside Chassis (OC) and stack it in CY
3	Export	Deliver container from CY to Apron (QC)
4	Import	Receive container from Apron (QC) and stack it in CY
5	Shifting	Stack and unstack of a container in CY (including rehandling, shift-in, shift-out)

Remark: CY: Container yard, QC : Quay crane, OC: Chassis from outside

2 Reconstructed Database

Year	Month	Date	Hour	Minute	Second	Latitude	Longitude	Battery SOC	Lift Speed	Travel Speed	Weight	Distance	Fuel Consumption	State of Brake	Loading Condition
1,14,2014,11,38,39,723	11	38,39,723	11	38	39	47.107,-55022.43	119.73,-0.2	100	0.12	187.04	4.4709	0,0,0,11199.632	0	0	0
1,14,2014,11,38,40,723	11	38,40,723	11	38	40	47.107,-55022.52	119.73,-0.2	100	0.12	187.04	4.4709	0,0,0,11200.305	0	0	0
1,14,2014,11,38,41,723	11	38,41,723	11	38	41	47.107,-55022.515	119.73,-0.2	100	0.12	187.04	4.4709	0,0,0,11201.754	0	0	0
1,14,2014,11,38,42,723	11	38,42,723	11	38	42	47.107,-55022.594	119.73,-0.4	663.0	0.11	201.754	1.199	0,0,0,11207.308	0	0	0
1,14,2014,11,38,43,723	11	38,43,723	11	38	43	47.107,-55024.693	119.73,-0.2	1400.88	20.0767	0,0,0,11218.656	0	0	0	0	0
1,14,2014,11,38,44,723	11	38,44,723	11	38	44	47.107,-55026.25	119.73,-0.2	1658.24	29.428	0,0,0,11223.099	0	0	0	0	0
1,14,2014,11,38,45,723	11	38,45,723	11	38	45	47.107,-55027.804	119.73,-0.2	1853.6	34.4218	0,0,0,11227.567	0	0	0	0	0
1,14,2014,11,38,46,723	11	38,46,723	11	38	46	47.107,-55029.729	119.73,-0.24	2066.24	38.1241	0,0,0,11231.734	0	0	0	0	0
1,14,2014,11,38,47,723	11	38,47,723	11	38	47	47.107,-55033.209	119.73,-0.4	2365.92	43.1956	0,0,0,11235.101	0	0	0	0	0
1,14,2014,11,38,48,723	11	38,48,723	11	38	48	47.107,-55035.22	119.73,-0.56	267	4	0,0,0,11237.231	0	0	0	0	0
1,14,2014,11,38,49,723	11	38,49,723	11	38	49	47.107,-55035.773	119.73,-0.56	267	4	0,0,0,11238.955	0	0	0	0	0
1,14,2014,11,38,50,723	11	38,50,723	11	38	50	47.107,-55036.142	119.73,-0.48	2613	1	0,0,0,11238.955	0	0	0	0	0
1,14,2014,11,38,51,723	11	38,51,723	11	38	51	47.107,-55036.419	119.73,-0.4	2409.28	9.9883	7,0,0,11238.955	0	0	0	0	0

Energy-Saving Analyzer Output

Battery utilization map

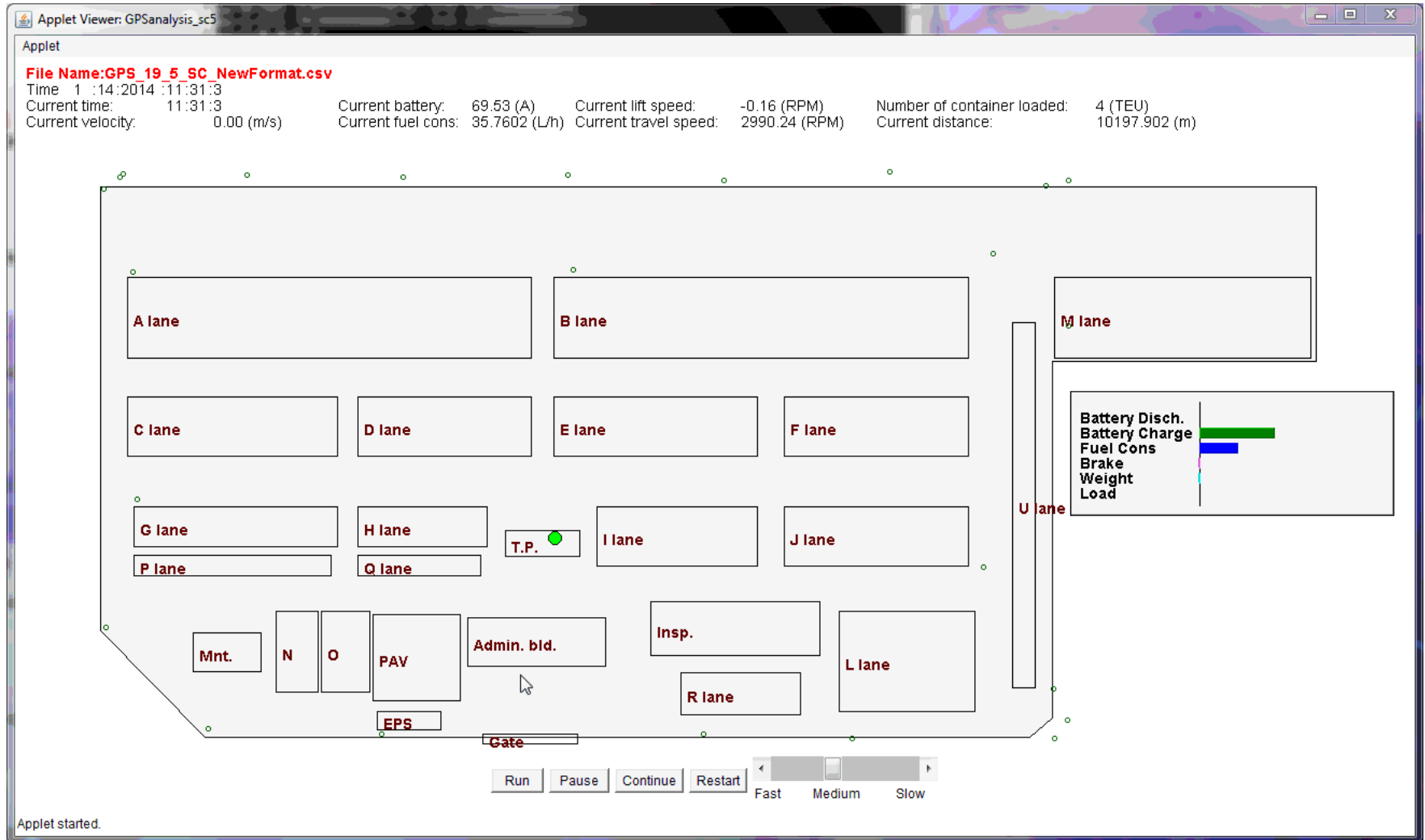


Battery state of charge

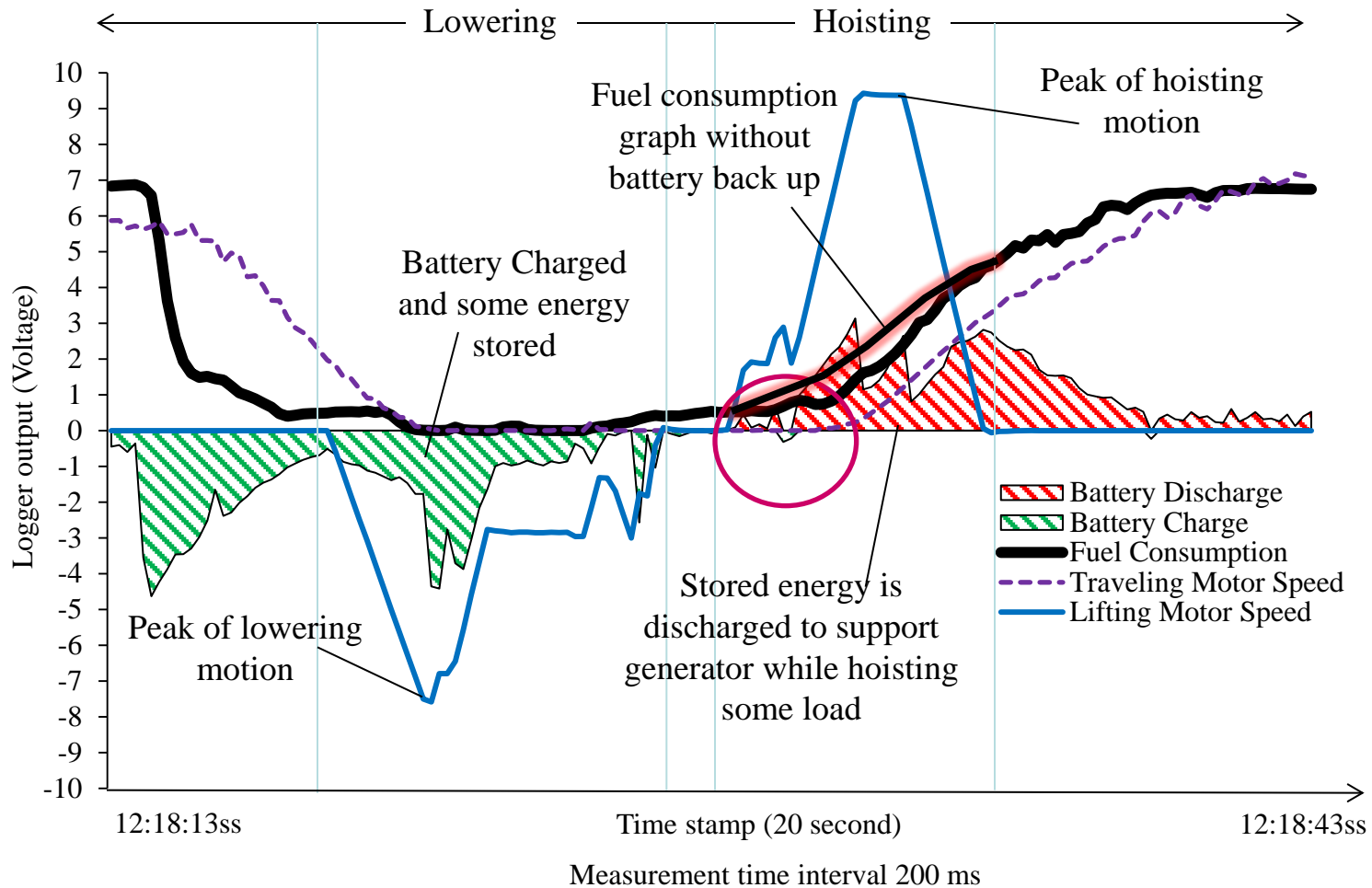


Battery state of discharge

Performance status will show exact amount of performance parameter when time elapsed as well as HSC's productivity



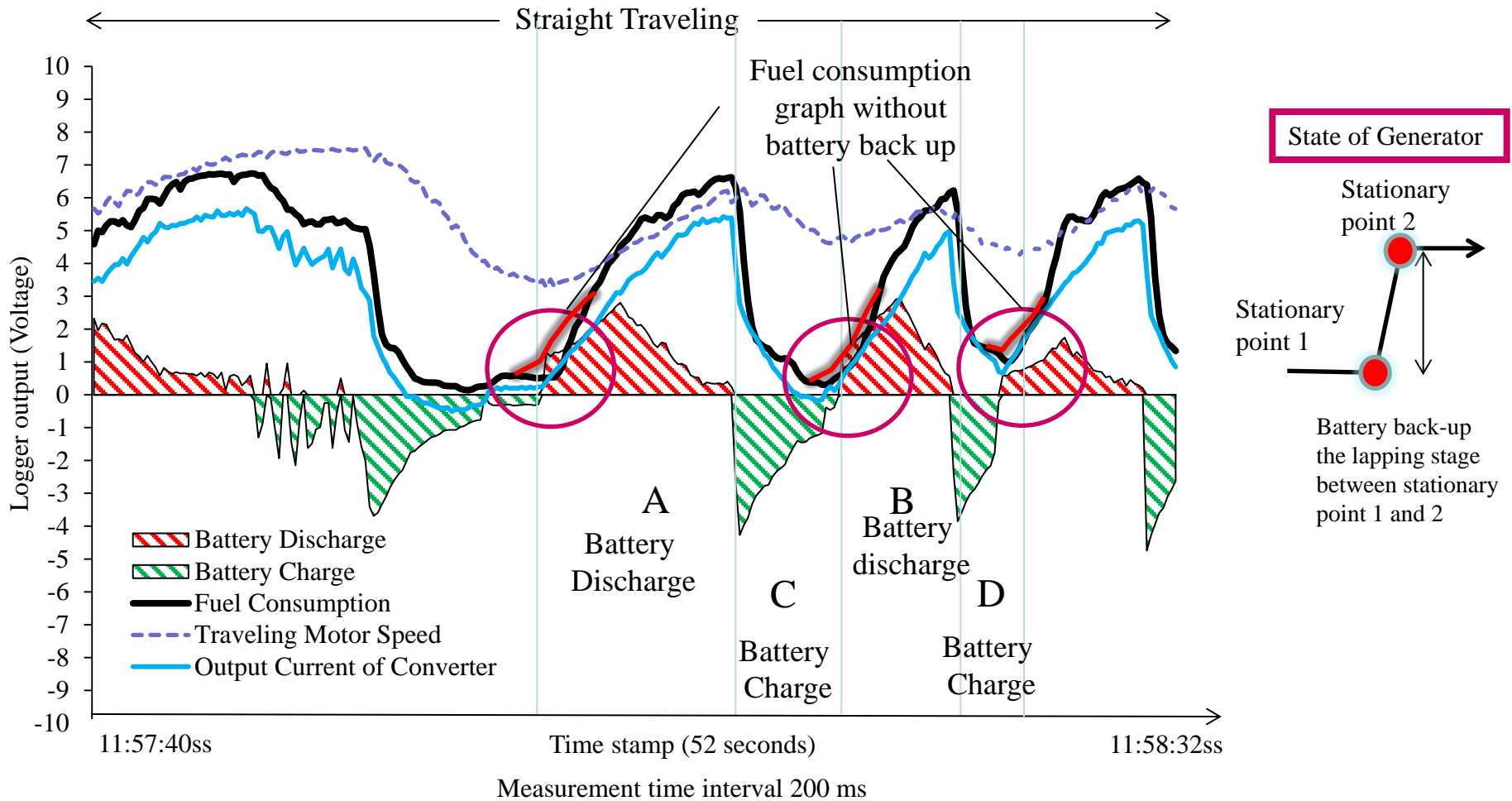
Benefit during vertical motion



Lowering the spreader generate some energy that will be stored in the battery.

The stored energy can be use to support generator when hoisting the spreader.
The benefit of this process is reduced fuel consumption while hoisting.

Benefit during horizontal motion

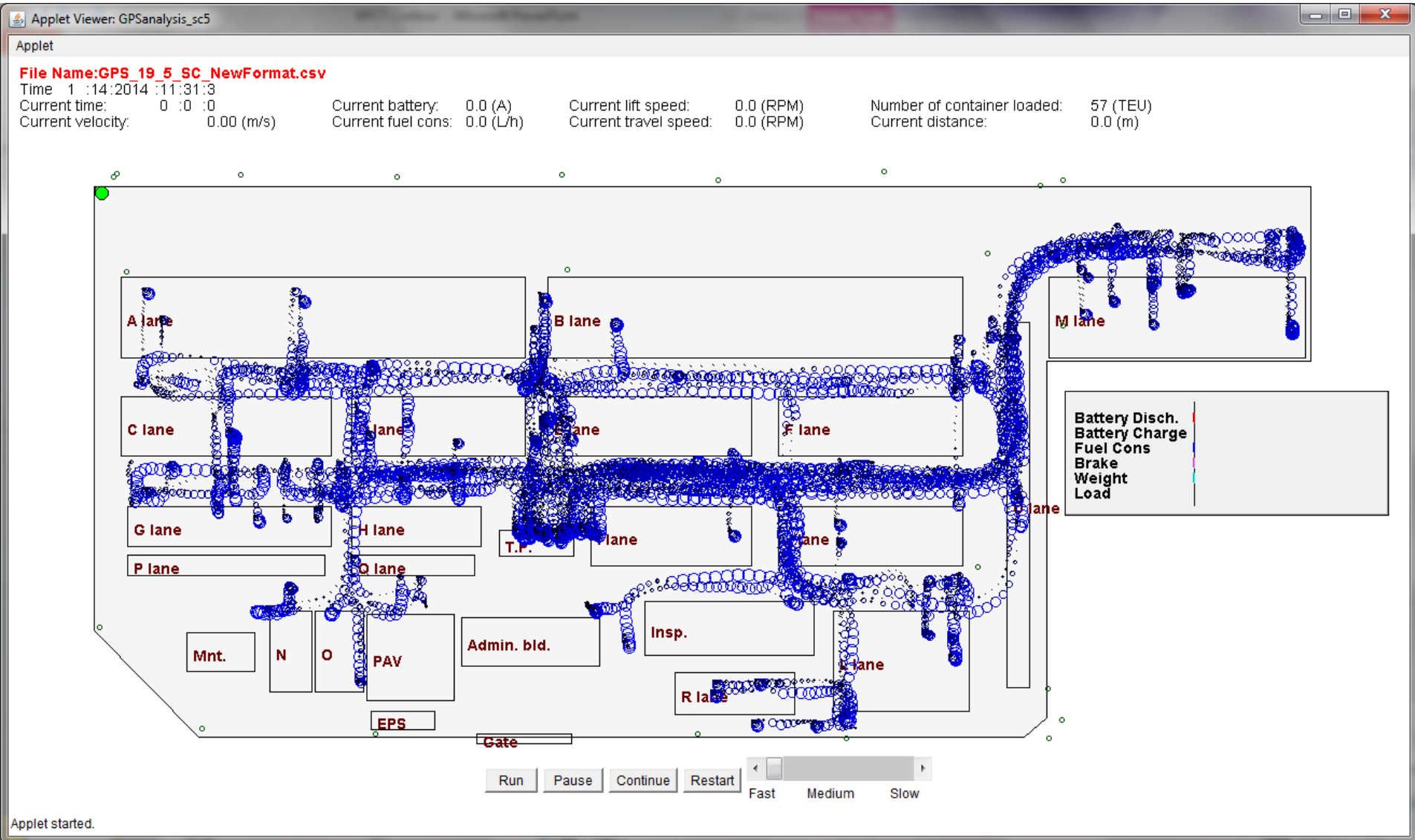


Discharging energy from battery to support the generator and reduce fuel consumption (Area A and B)

When lowering the speed and deaccelerate, vehicle can gain some energy charge from wheel rotation (Area C and D)

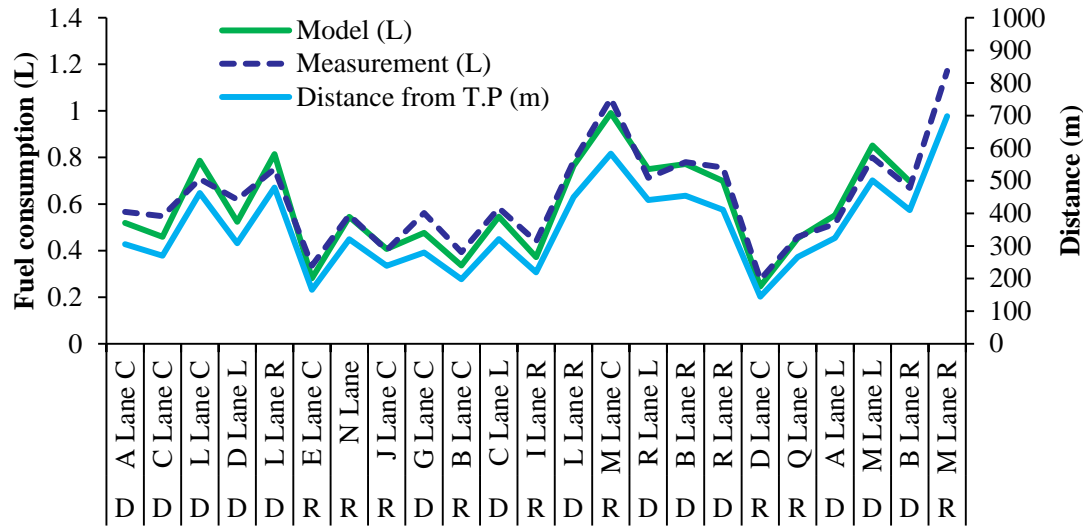
Energy-Saving Analyzer Output

Fuel consumption map



Result from modeling operation performance of HSC (half day)

All route is start from transfer point (T.P) to various stack position and simulated routes were compared to actual operation in database



$$\text{Total } F = F_{vertical} + F_{horizontal}$$

Total fuel consumption for a specific route = Total fuel consumption for vertical motion + Total fuel consumption for horizontal motion

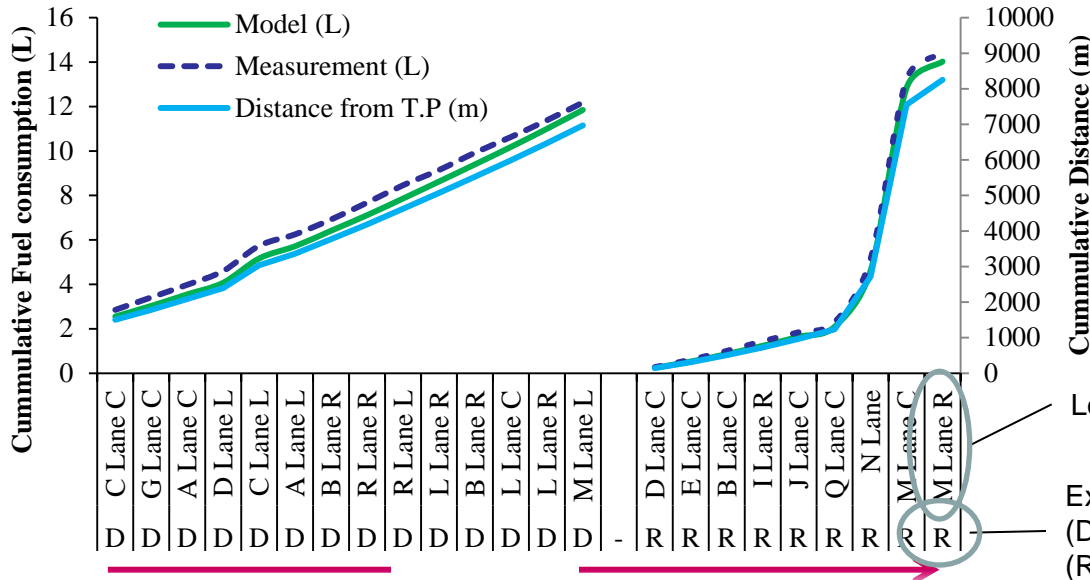
$$F_{vertical} = F_h + F_l$$

fuel consumption from **hoisting** + fuel consumption from **lowering**

$$F_{horizontal} = F_t + F_c + F_m$$

fuel consumption for **straight traveling** + fuel consumption for **cornering** + fuel consumption from **maneuvering**

Putting together the measurement result, we attempted to model the movement of HSC by calculating point-to-point distance and compare it to measurement result.



Location (Lane and Position) in Yard

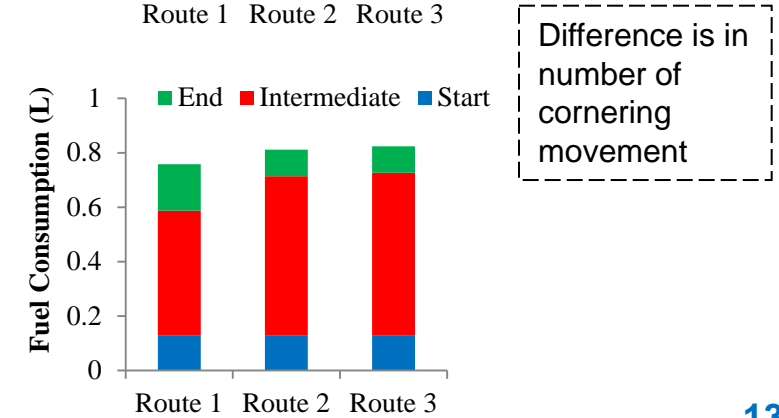
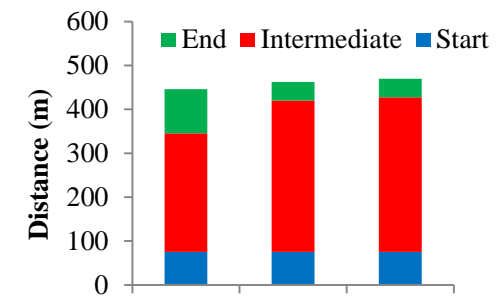
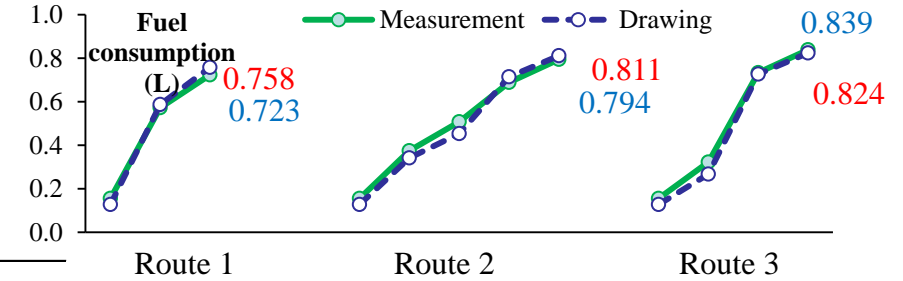
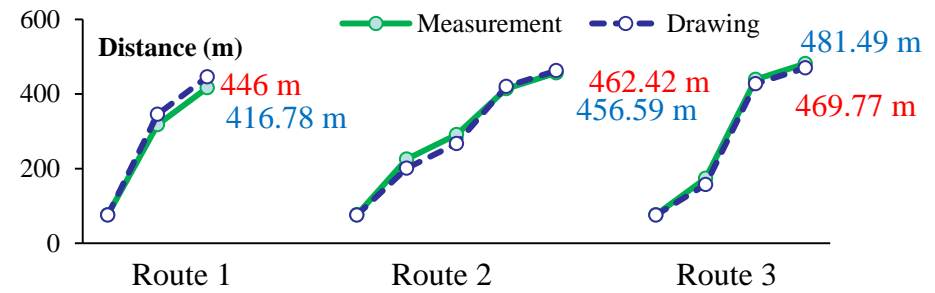
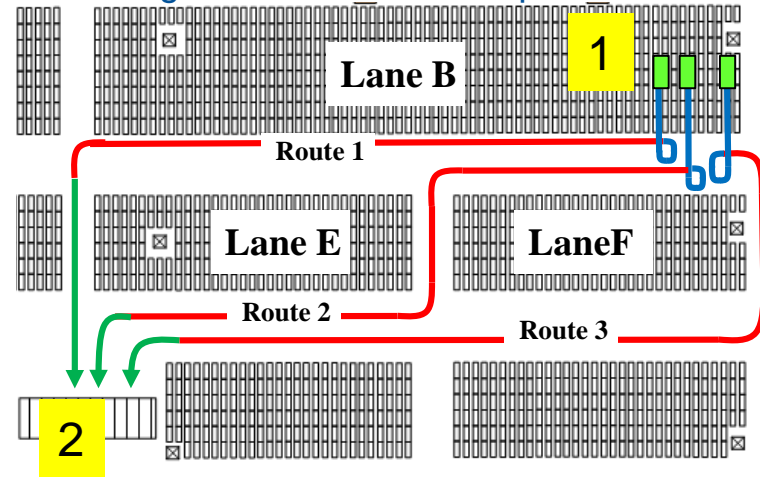
Explain operation work code status
(D): Delivery
(R): Receipt

3:43:22 ss

3:16:00 PM

Calculating best route for specific task

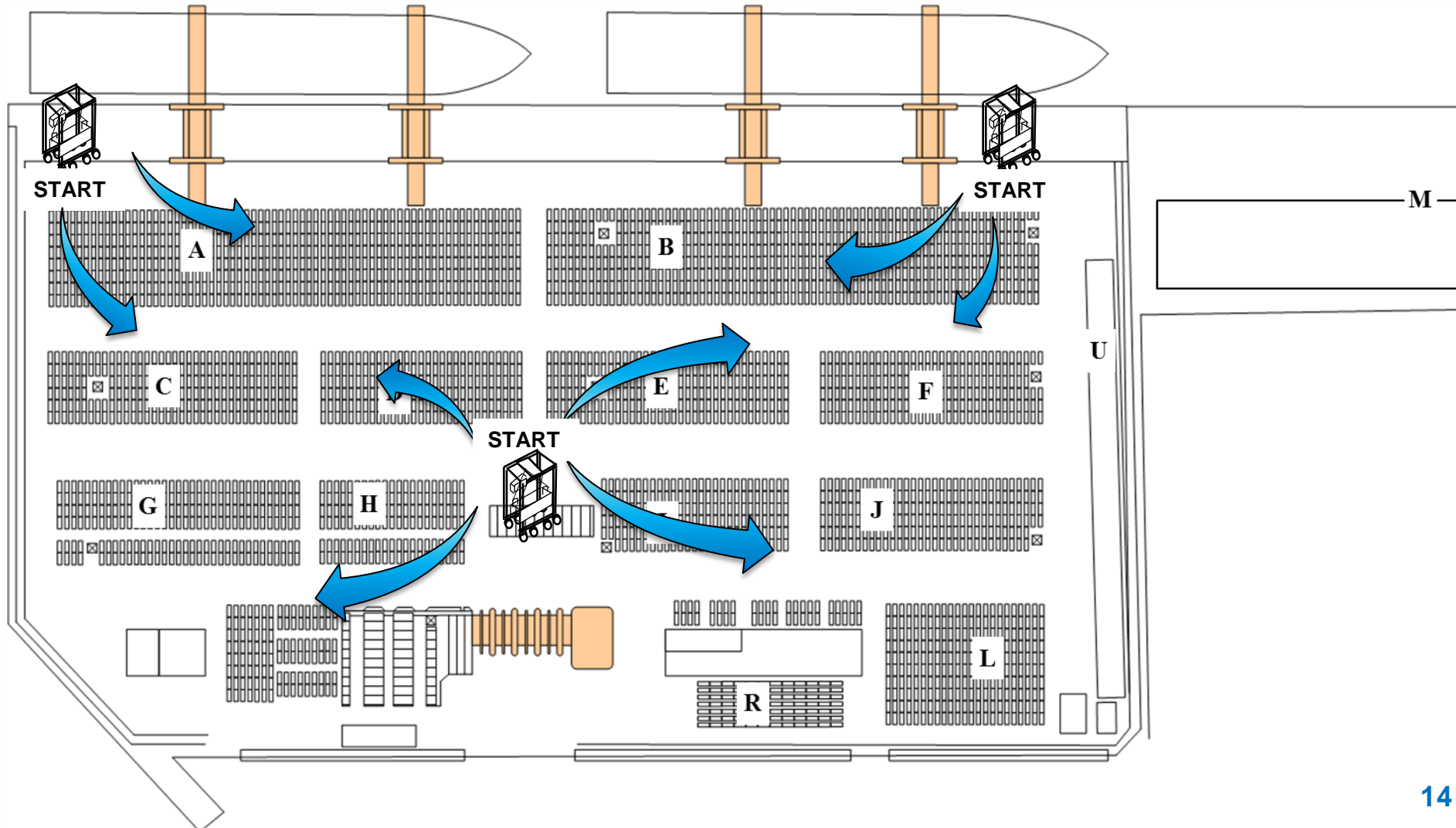
There might be several route option for each task



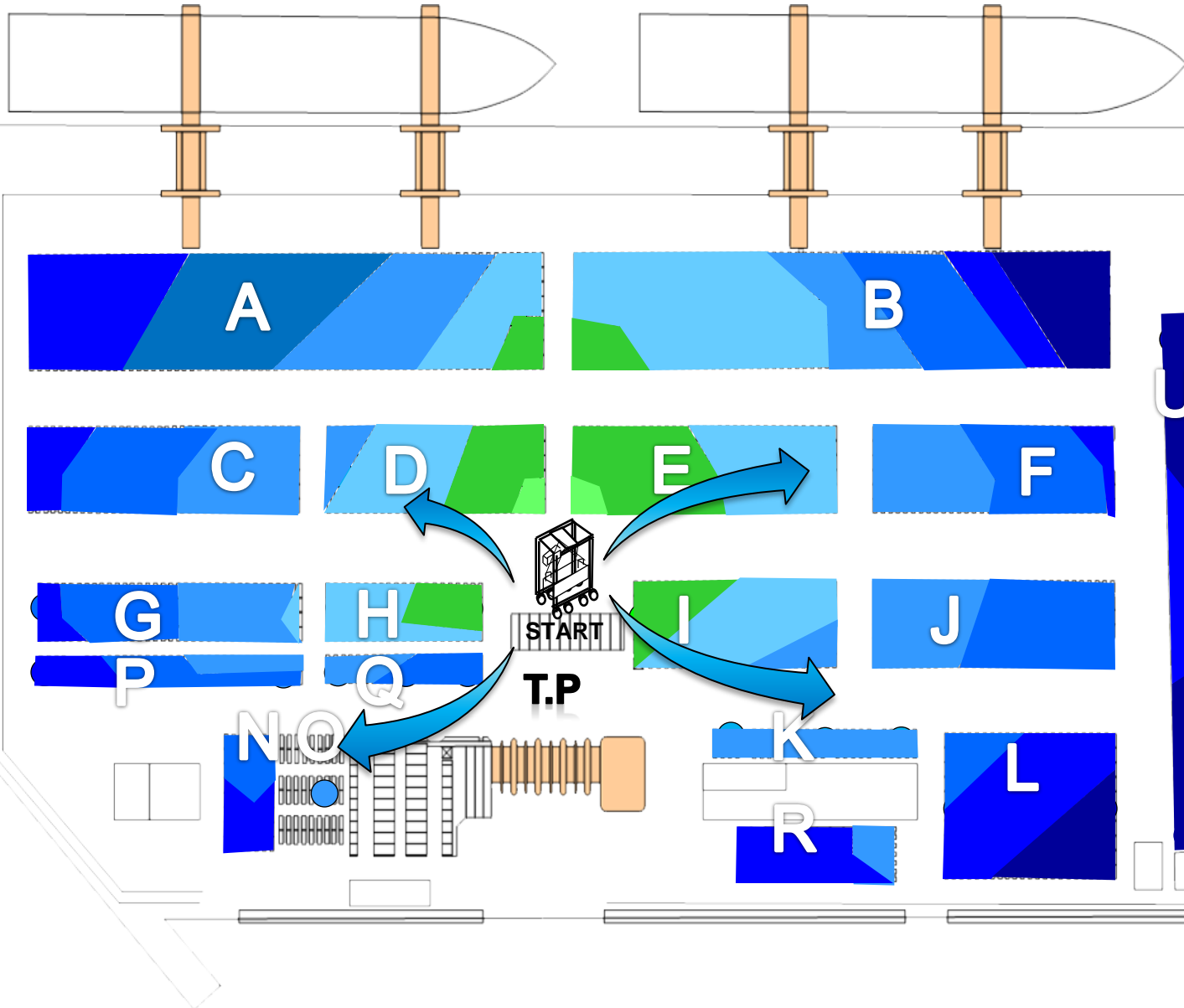
COMPARISON	Num of data	Distance (m)		FC (L)	
		Measurement	Model	Measurement	Model
Route 1					
B Lane RB - B Lane RR	8	75.93	75.25	0.16	0.13
B Lane RR - B Lane LR	2	241.63	270.28	0.42	0.46
B Lane LR - TP	3	99.22	100.48	0.15	0.17
Total	13	416.78	446.00	0.72	0.76
Route 2					
B Lane RB - B Lane RR	8	75.93	75.25	0.16	0.13
B Lane RR - B Lane CR	1	149.61	125.65	0.22	0.21
B Lane CR - E Lane RR/F Lane LR	1	65.59	65.95	0.13	0.11
E Lane RR/F Lane LR - E Lane LR	7	123.07	153.27	0.18	0.26
E Lane LR - TP	9	42.39	42.30	0.11	0.10
Total	26	456.60	462.42	0.79	0.81
Route 3					
B Lane RB - B Lane RR	8	75.93	75.25	0.16	0.13
B Lane RR - F Lane RR	2	98.14	81.95	0.17	0.14
F Lane RR - E Lane LR	8	265.03	270.28	0.41	0.46
E Lane LR - TP	9	42.39	42.30	0.11	0.10
Total	27	481.50	469.78	0.84	0.82

Simulating HSC Movement

After knowing the best route for each point-to-point task, we can help to simulate HSC movement to all the position in the yard to create fuel consumption map

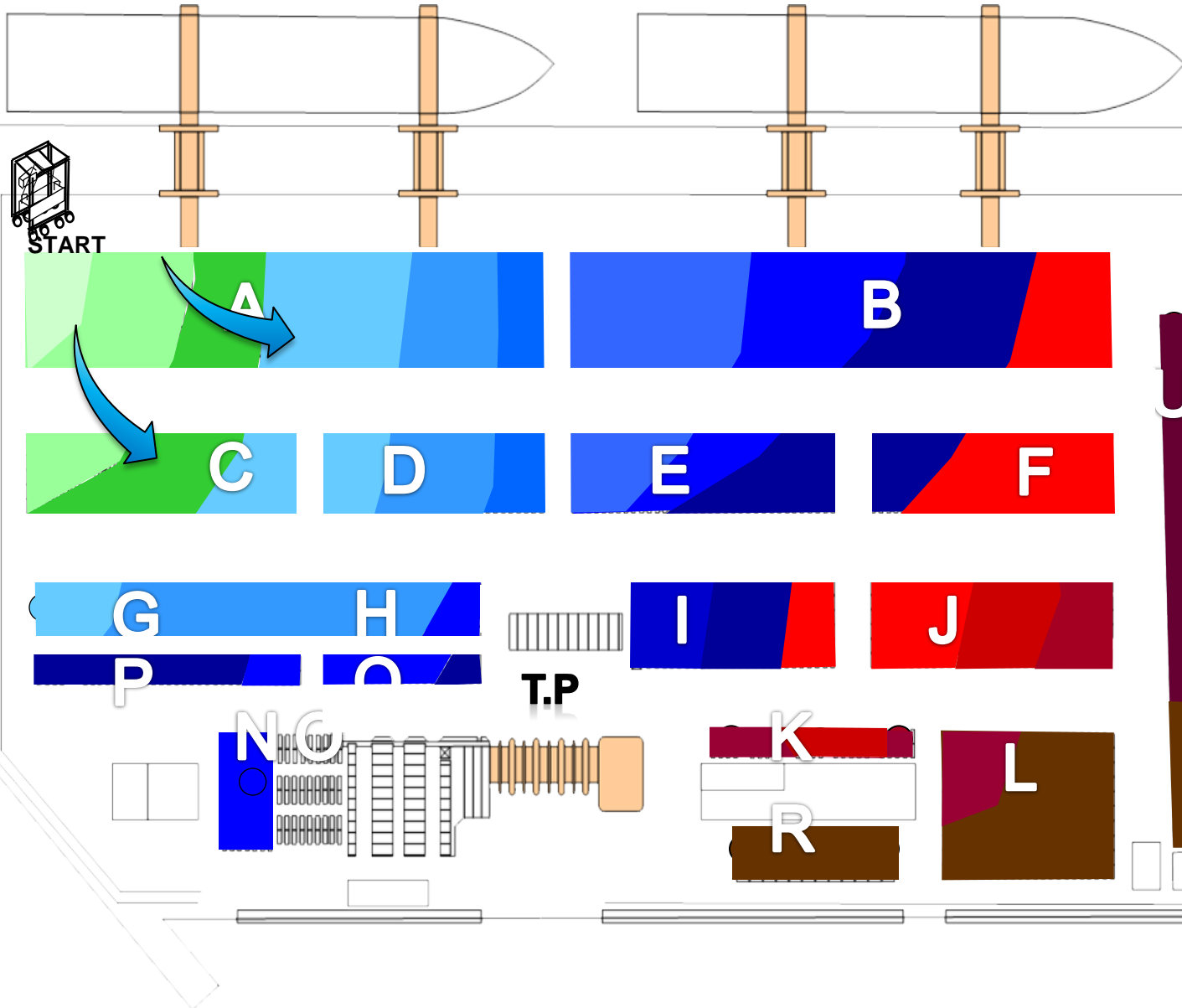


Example of Fuel Consumption Map (1)



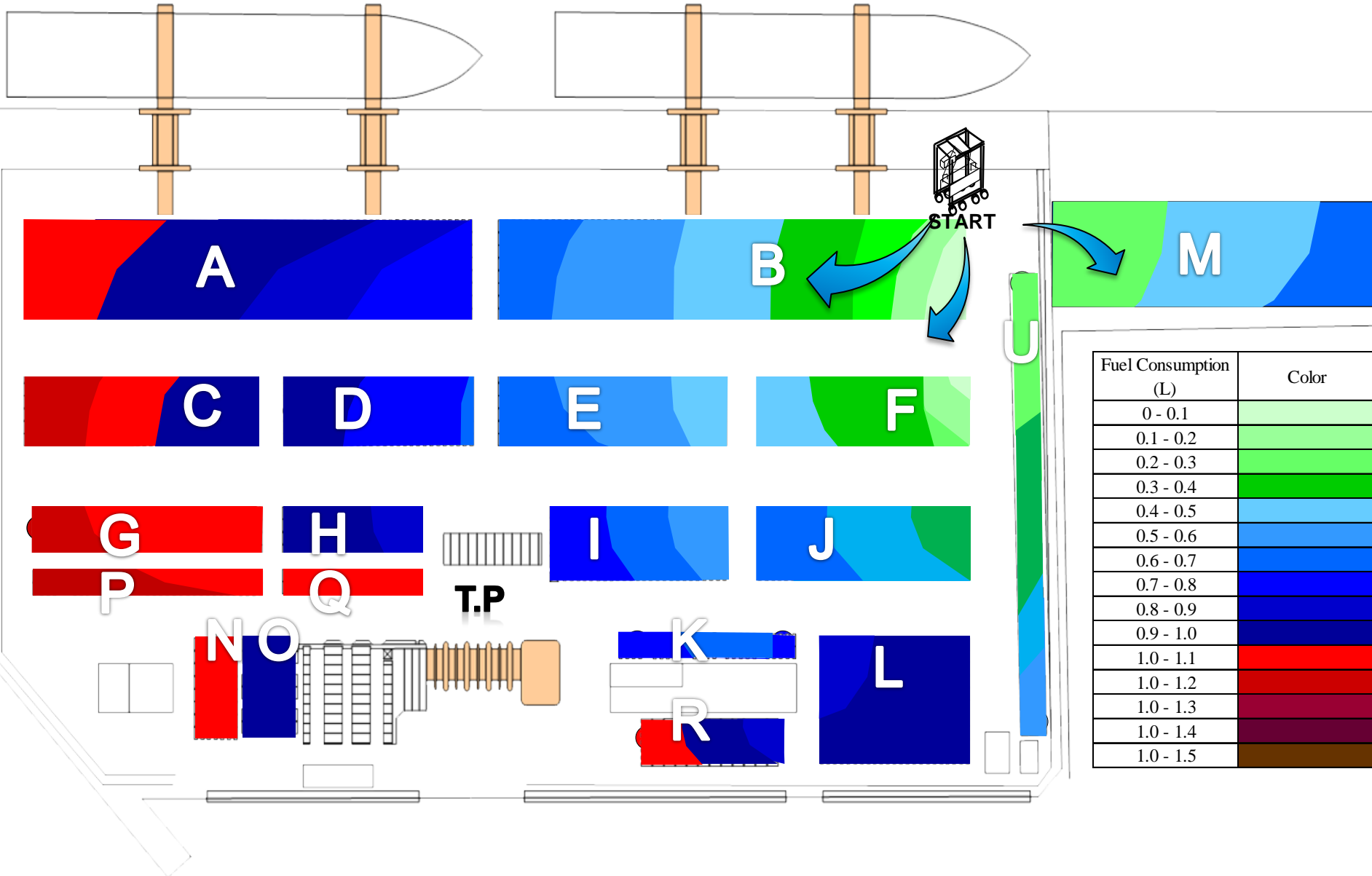
Fuel Consumption (L)	Color
0 - 0.1	Lightest Green
0.1 - 0.2	Light Green
0.2 - 0.3	Medium Green
0.3 - 0.4	Dark Green
0.4 - 0.5	Light Blue
0.5 - 0.6	Medium Blue
0.6 - 0.7	Dark Blue
0.7 - 0.8	Very Dark Blue
0.8 - 0.9	Dark Blue
0.9 - 1.0	Dark Blue
1.0 - 1.1	Red
1.0 - 1.2	Dark Red
1.0 - 1.3	Dark Purple
1.0 - 1.4	Dark Purple
1.0 - 1.5	Brown

Example of Fuel Consumption Map (2)



Fuel Consumption (L)	Color
0 - 0.1	Lightest Green
0.1 - 0.2	Light Green
0.2 - 0.3	Green
0.3 - 0.4	Dark Green
0.4 - 0.5	Light Blue
0.5 - 0.6	Blue
0.6 - 0.7	Dark Blue
0.7 - 0.8	Very Dark Blue
0.8 - 0.9	Dark Blue
0.9 - 1.0	Red
1.0 - 1.1	Dark Red
1.0 - 1.2	Dark Red
1.0 - 1.3	Dark Purple
1.0 - 1.4	Dark Purple
1.0 - 1.5	Dark Brown

Example of Fuel Consumption Map (3)

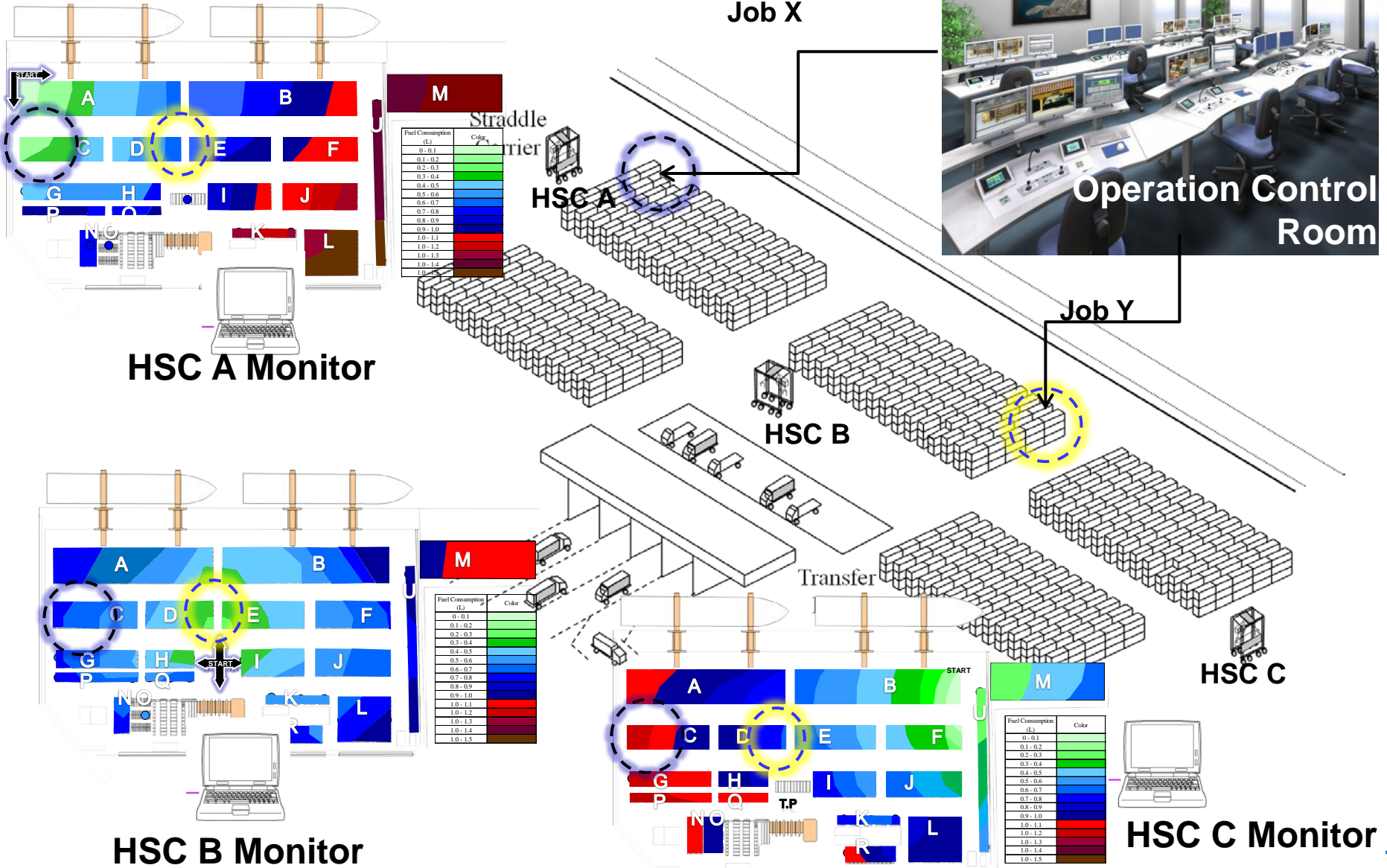


How fuel consumption map help efficient utilization of HSC

Driver choose to accept/not accept job order considering their position in yard and impact to fuel consumption



Operation Control Room



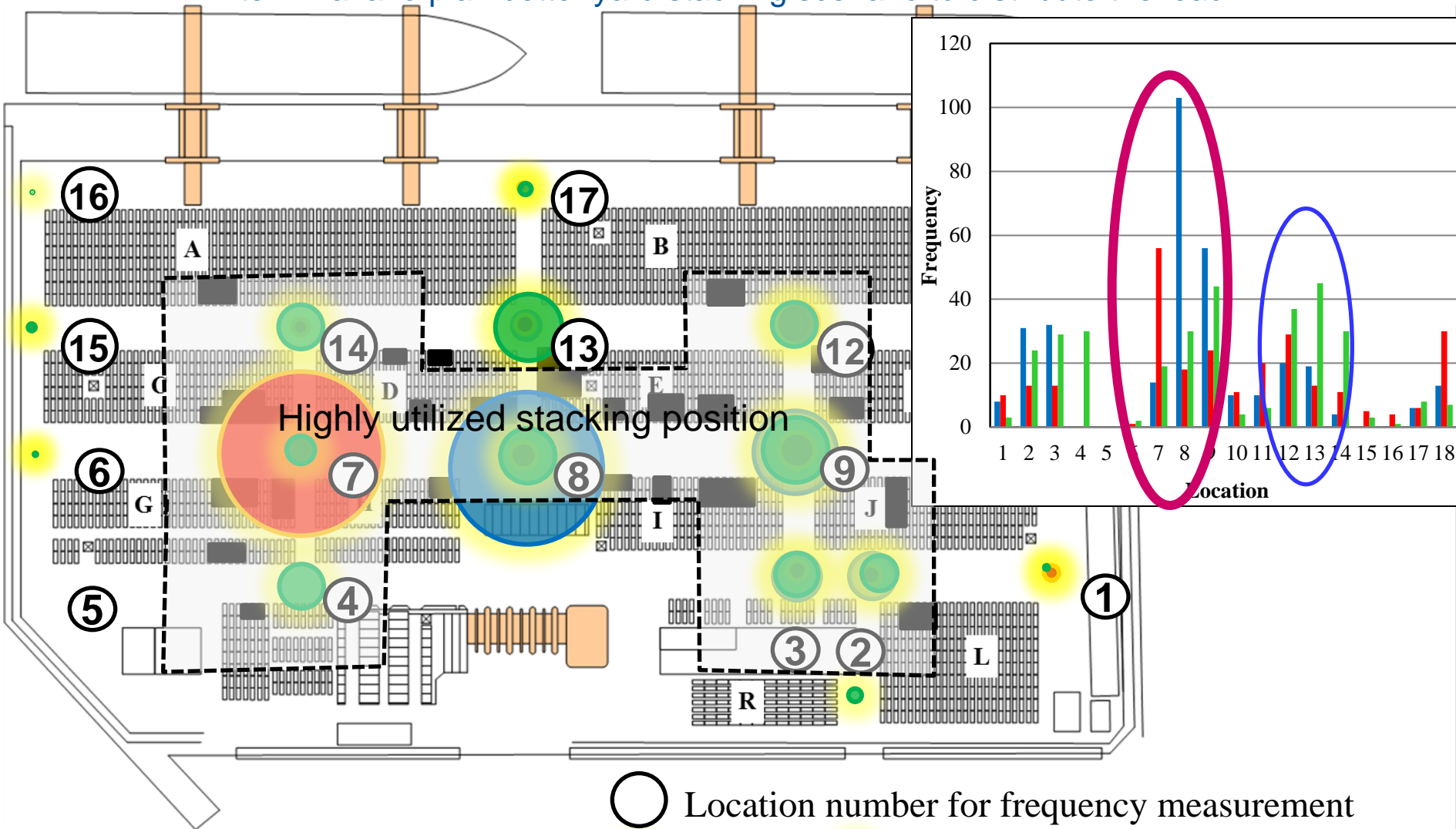
HSC A Monitor

HSC B Monitor

HSC C Monitor

Density Map at intersections

By knowing the density at intersection, we can predict the operation pattern in the container terminal and plan better yard stacking scenario to distribute the load



Scale of frequency :
1 frequency \equiv 0.1" of circle diameter

- Day 1
- Day 2
- Day 3

Conclusion

Support tools for environmental initiative

1

Visualization of energy analysis able to extract valuable information which were not able to be shown with aggregate calculation such as Battery utilization map and Fuel consumption map

Output from the analyzer can be used to model the movement all over the yard.

Visualizing energy analysis

2

Fuel map can be of help to organize efficient routing of straddle carrier

By knowing the density map, we can help to plan better yard utilization to reduce Yard Occupancy and reduce double handling

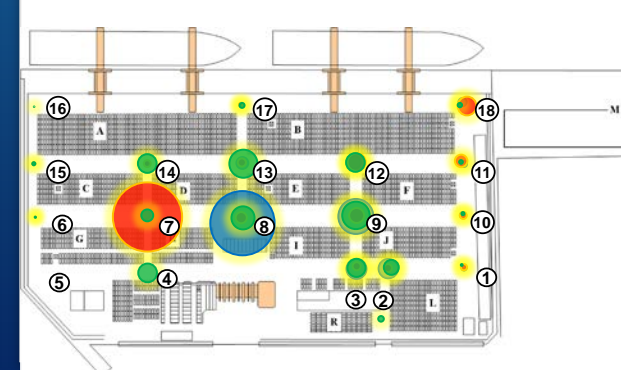
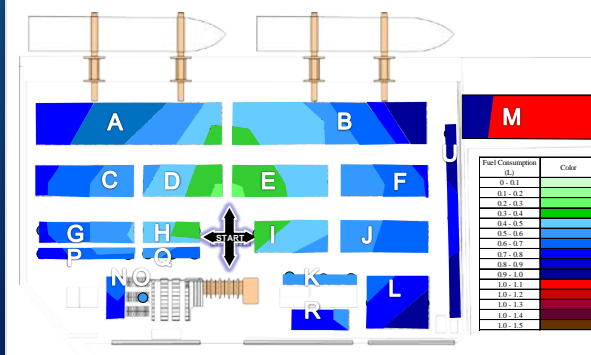
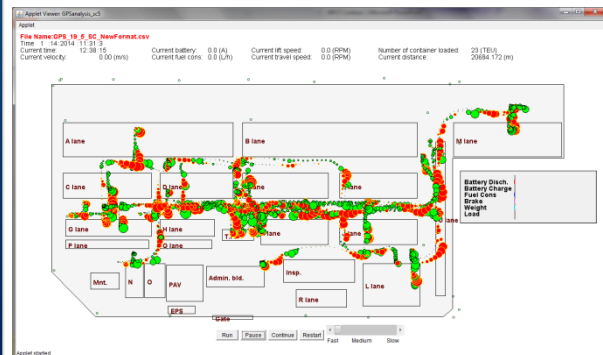
This method can be applied generally to any kind of handling equipment

Final Target: Energy-Saving

3

The final target is to use dynamic simulation to investigate energy-saving performance for all handling equipment

We will consider also various operation constraint to improve the accuracy of the model



THANK YOU FOR YOUR ATTENTION